



# Qualification of a Commercial Dual Frequency GPS Receiver for the e-POP Platform onboard the Canadian CASSIOPE Spacecraft

Richard B. Langley<sup>(1)</sup>, Oliver Montenbruck<sup>(2)</sup> Makus Markgraf<sup>(2)</sup>, Don Kim<sup>(1)</sup>

<sup>(1)</sup> Geodetic Research Laboratory Dept. of Geodesy and Geomatics Engineering University of New Brunswick Fredericton, N.B., Canada <sup>(2)</sup> Space Flight Technology German Space Operations Center Deutsches Zentrum f
ür Luft- und Raumfart Wessling, Germany

RBL/ESA 10Dec04



# CASSIOPE



### • CASSIOPE = CAScade-demonstrator Smallsat and Ionospheric Polar Explorer

(also low tufted evergreen shrubs of colder parts of north temperate regions having mosslike foliage and nodding white or pink flowers; a.k.a. heather)

- Canada's first multipurpose satellite
- Merger of CASCADE (very wide bandwidth store-and-forward data delivery platform) with e-POP (enhanced - Polar Outflow Probe)
- Planned 2007 launch

RBL/ESA 10Dec04



# Players



- Funded by the Canadian Space Agency and the Natural Sciences and Engineering Research Council of Canada
- e-POP team includes researchers at 10 Canadian universities plus government agencies in Canada, the U.S.A., and Japan
- Chief e-POP scientist: Andrew Yau, U.ofC.
- CASSIOPE spacecraft prime: MDA
- Spacecraft bus: Bristol Aerospace

RBL/ESA 10Dec04







Semi-major axis	7280 km
Eccentricity	0.08
Apogee	1500 km
Perigee	325 km
Inclination	80°





- Imaging Rapid-scanning Ion Mass Spectrometer (IRM)
- Suprathermal Electron Imager (SEI)
- Magnetic Field Instrument (MGF)
- Fast Auroral Imager (FAI)
- Radio Receiver Instrument (RRI)
- Neutral Mass and Velocity Spectrometer (NMS)
- Coherent Electromagnetic Radiation (CER)
- GPS Attitude and Profiling Experiment (GAP)



CASSIOPE





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





The GPS Attitude and Profiling instrument is multipurposed. It will determine:

- spacecraft three-dimensional position, velocity, and attitude
- time referenced to UTC
- ionospheric electron density profiles

#### Functions divided into GAP-A and GAP-O



# GAP Objectives-2



#### GAP-A

- Position, velocity, attitude, and time can be determined in real time and made available to other spacecraft systems:
  - position to 100 metres
  - velocity to 10 metres per second
  - attitude to 5 degrees
  - time to 1 microsecond
- More accurate results will be achievable from down-linked data including attitude to 0.5 degrees.

RBL/ESA 10Dec04





### GAP-O

- Electron density profiling using antenna pointed in anti-ram direction
- High-rate measurements on setting (occulted) GPS satellites together with measurements from non-occulted satellites down linked to ground for analysis
- Analysis will provide high resolution profiles of electron density in the ionosphere and plasmasphere
- Not mandated to profile neutral atmosphere (likely insufficient antenna gain)





- Early in mission design, decision made to base GAP instrument on multiple COTS dual-frequency receivers
- Decision based on economics
- NovAtel OEM4-G2L selected



#### NovAtel OEM4-G2L





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004



#### NovAtel OEM4-G2L





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





- Instrument consists of:
  - An interface card
  - Power supply card
  - 5 GPS cards (includes one spare)
  - 5 GPS antennas and LNAs
  - Antenna/LNA switch
- GAP-A and GAP-O functions combined into a single instrument



NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004



#### Instrument Overview









- A series of tests have been carried out to see if the OEM4-G2L could withstand the rigors of spaceflight:
  - Tracking
  - Radiation
  - Thermal vacuum





- Simulator tests carried out on an OEM4-G2 by DLR at the ESA/ESTEC RNL in Noordwijk
- Orbit used: CHAMP
- Real-time solutions and raw data quality assessed
- Test results demonstrated that the receiver could track GPS satellites with unmodified, standard firmware



#### Navigation Accuracy





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





 Total ionizing dose (TID) tests by DLR at Fraunhofer Institute for Technological Trend Analysis using Co-60 gamma ray source

> RBL/ESA 10Dec04



### Total Ionizing Dose Test Setup





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





- Applied total dose limited to 10 krad in an effort to avoid a destructive test
- Dose rate of 1 rad per second for about 3 hours
- Receiver continuously operated; no apparent malfunction noted during and immediately after the test
- Some increase in current consumption during the test



### **Current Consumption**





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





- Several days after the test, the receiver failed to operate
- Post-mortem analysis by NovAtel indicated a failed microprocessor
- Radiation damage or some other cause such as electrostatic discharge?
- Second test planned





- 2 new receivers tested
- Receiver power cycled off and back on several times during the test
- First receiver rebooted at 3.6 krad and 7.2 krad; failed to reboot at 7.2 krad
- Second receiver rebooted every 1 krad; failed at 6 krad reboot; came back to life after a few days
- Testing on first receiver indicated failed low-voltage monitor (TCM811)





- Replacing the TCM811 with a manual reset circuit returned receiver to normal operation
- For flight, all TCM811s will be removed from boards and reset logic will be provided on the GAP interface card





- OEM4-G2L board subjected to TVAC test at Bristol Aerospace
- Receiver tested (while operating) from -35°C (-40°C unpowered) to +50°C under a vacuum of 10<sup>-5</sup> torr
- Minos-4 ASIC removed, thermal compound added and resoldered to board
- Board outfitted with about 13 thermistors



## PreliminaryAmbient Conditions Test





NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004









NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004









NAVITEC '2004 • Eurpean Space & Technology Centre, Noordwijk, The Netherlands • 8-10 December 2004





- Receiver performed normally throughout the test based on post-processing collected data
- Temperature of hotest component on the board was only about 22°C different from temperature of thermal control plate
- Power consumption near nominal; about 200 mW more at extreme high temperature





- Good evidence for proper functioning of the NovAtel OEM4-G2L receiver in low Earth orbit with only minor board changes required
- Opens up new prospects for future low-cost science missions





- Canadian Space Agency
- Natural Sciences and Engineering Research Council of Canada
- Fraunhofer Institute for Technological Trend Analysis
- Bristol Aerospace
- MacDonald, Dettwiler & Associates (MDA)